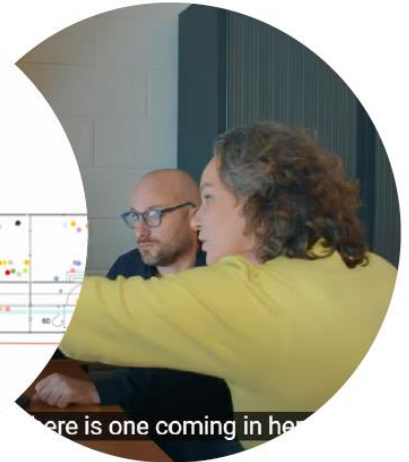
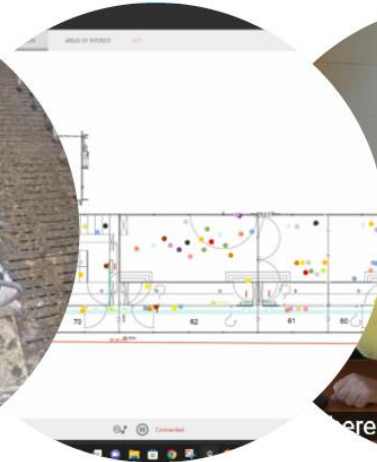


# Continuous and non-invasive monitoring of animals using sensors and computer vision analysis

Wageningen University & Research – Animal Science Group

Noldus Information Technology



# Outline

## **Current situation and future perspective**

General description of the project

Data architecture at Dairy Campus

- Installation of hardware and software

- Data quality control

Tools to retrieve relevant information from raw sensor data

- Locomotion parameters of individual animals

- Continuous monitoring of behaviour in groups of animals

- Automated behaviour in the barn

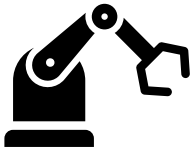
- Transmission of Digital Dermatitis

Output

# Current situation and future perspective

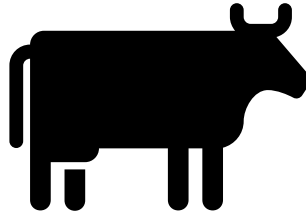
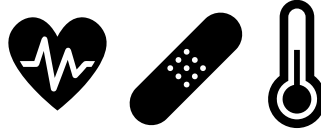
Animal health and welfare are one of the pillars for sustainable farming.

Animal health and welfare is often monitored through (deviant) behaviour



## By farmers/experts/sensors:

No continuous information  
Often more severe cases  
Time consuming  
Subjective  
Indirect



## By camera/tracking

Continuous  
Scalable  
Objective  
Non-invasive



# Outline

Current situation and future perspective

## **General description of the project**

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- Automated behaviour in the barn

- Transmission of Digital Dermatitis

Output

# General description of the project

## **Vision:**

Non-invasive long-term continuous monitoring of health & welfare

## **Partners:**

WUR-ASG and Noldus Information technology with financial support from the Dairy Campus Innovation Fund funded by SNN

## **Duration of the project:**

June 1, 2021 – September 30, 2023

## **Location of research:**

Dairy Campus and Wageningen, the Netherlands

# General description of the project

## Focus of project:

**Behaviour** related to **Locomotion** and transmission of **Digital Dermatitis** using tracking data and computer vision

## Research focus is 2-fold:

1. Develop **data architecture** at Dairy Campus (DC) for long-term continuous raw data collection and synchronisation with data quality control throughout the process
2. Develop **tools** to retrieve relevant information for (behaviour related to) locomotion and Digital Dermatitis from these raw sensor data

# Outline

Current situation and future perspective

General description of the project

## **Data architecture at Dairy Campus**

- Installation of hardware and software

- Data quality control

Tools to retrieve relevant information form raw sensor data

- Locomotion parameters of individual animals

- Continuous monitoring of behaviour groups of animals

- Automated behaviour in the barn

- Transmission of Digital Dermatitis

Output

# Data architecture at Dairy Campus

## Objective

Develop architecture at Dairy Campus that allows long-term continuous collection and synchronisation of raw sensor data collected at different locations within DC. Ensure data quality is controlled throughout the process

## What is achieved

Installation of hardware and software at different locations within DC

Pipelines for data quality control





# Outline

Current situation and future perspective

General description of the project

Data architecture at Dairy Campus

*Installation of hardware and software*

Data quality control

Tools to retrieve relevant information from raw sensor data

Locomotion parameters of individual animals

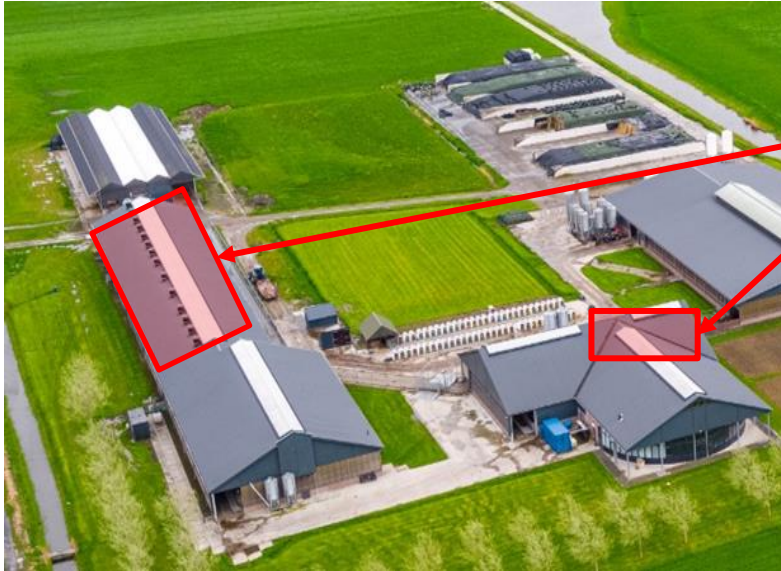
Continuous monitoring of behaviour groups of animals

Automated behaviour in the barn

Transmission of Digital Dermatitis

Output

# Installation of hardware and software



## UWB Tracking sensors

(TrackLab, Noldus Information Technology)

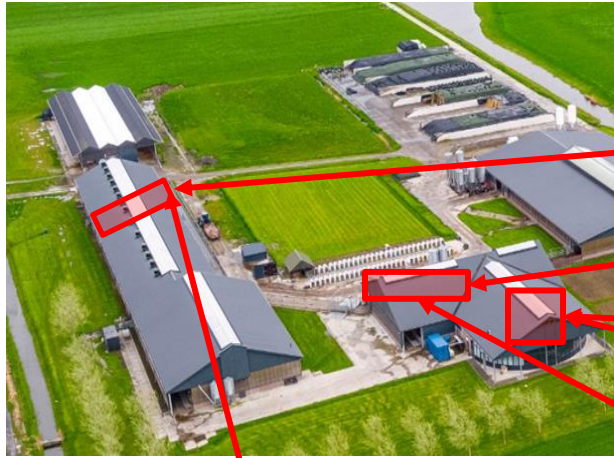
7 research units, 110 cows, 24/7 XY en accelerometer data

Waiting area, 110 cows, 2x/day XY en accelerometer data

**Network extension for IP cameras and beacons**



# Installation of hardware and software



## Cameras at three locations

8 camera's in 1 research unit, 16 cows, 24/7, birdview  
(Viso system, Noldus Information Technology)

2 camera's in 'exit lane', 110 cows, sideview, 2x/day

2 camera's in milking parlour, >400 cows, hind view, 2x/day



# Outline

Current situation and future perspective

General description of the project

Data architecture at Dairy Campus

Installation of hardware and software

*Data quality control*

Tools to retrieve relevant information from raw sensor data

Locomotion parameters of individual animals

Continuous monitoring of behaviour groups of animals

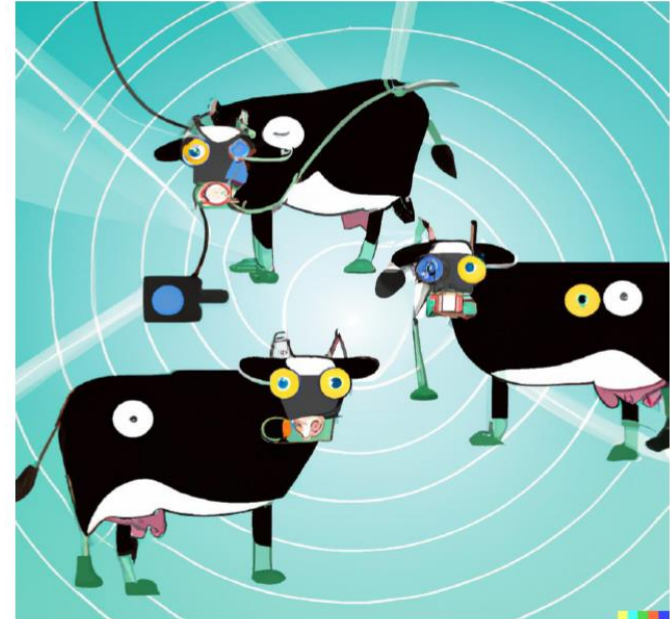
Automated behaviour in the barn

Transmission of Digital Dermatitis

Output

# Data quality control

Control of data quality is extremely important. Tools are developed to control quality at different locations and at different levels



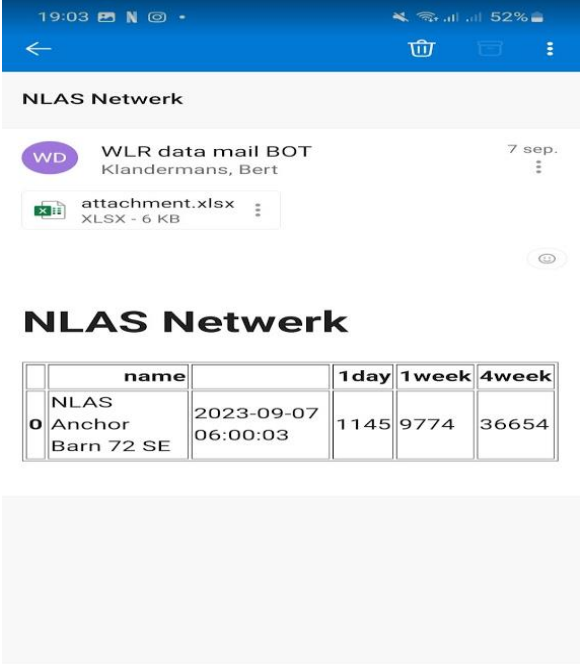
# Data quality control

Control of data quality is extremely important. Tools are developed to control quality at different locations and at different levels

## At network level

Continuous check (every minute a day) of the functioning of hardware

If not functioning: an email is generated and sent to the data engineer at Dairy Campus



The screenshot shows an email interface. At the top, the sender is identified as 'WLR data mail BOT' from 'Klandermans, Bert', dated '7 sep.'. An attachment named 'attachment.xlsx' (6 KB) is visible. Below the email content, there is a table titled 'NLAS Network' with the following data:

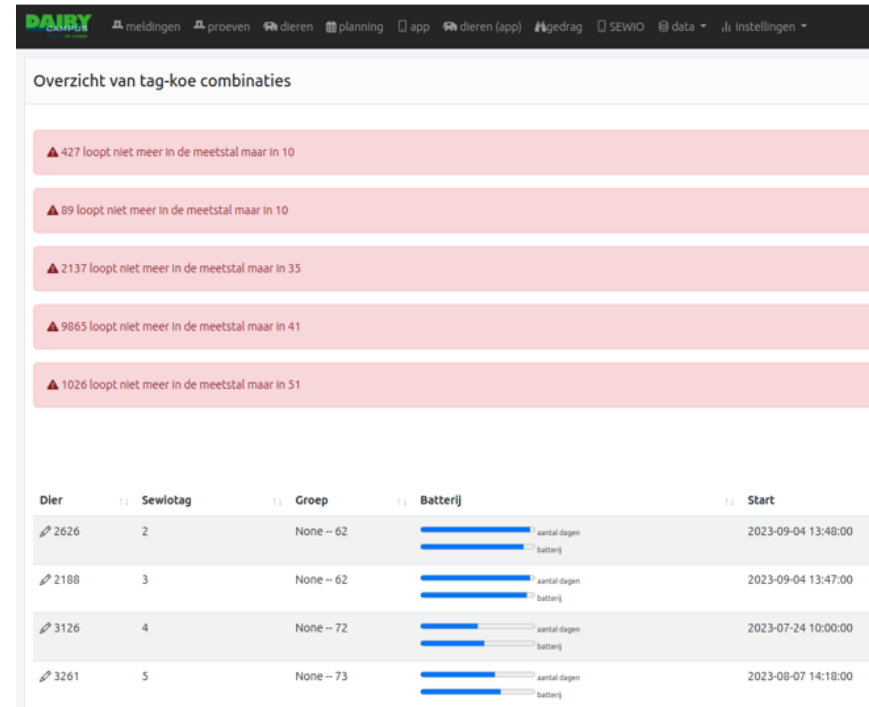
	name		1day	1week	4week
0	NLAS Anchor Barn 72 SE	2023-09-07 06:00:03	1145	9774	36654

# Data quality control

Control of data quality is extremely important. Tools are developed to control quality at different locations and at different levels

## At tag level

digital tool to record which tag  
fitted on which cow  
are cows in the right research unit  
battery status of tags



# Data quality control

Control of data quality is extremely important. Tools are developed to control quality at different locations and at different levels

## At raw data level

pipelines developed to collect and store raw data, e.g. for tracking data

Pipeline in words: 1 export raw data from Sewio data base to WLR data base; 2 export datasets of one hour from WLR data base to secured location WLR; 3 aggregate data to 1 XY position per second, add cow identification; 4 create datasets of 24h; 5 Implement filters to clean data, impute missing values and classify position of cow in barn based on XY position. Based on position in barn define behaviour; 6 add average behaviour per minute per cow to Dairy Campus database



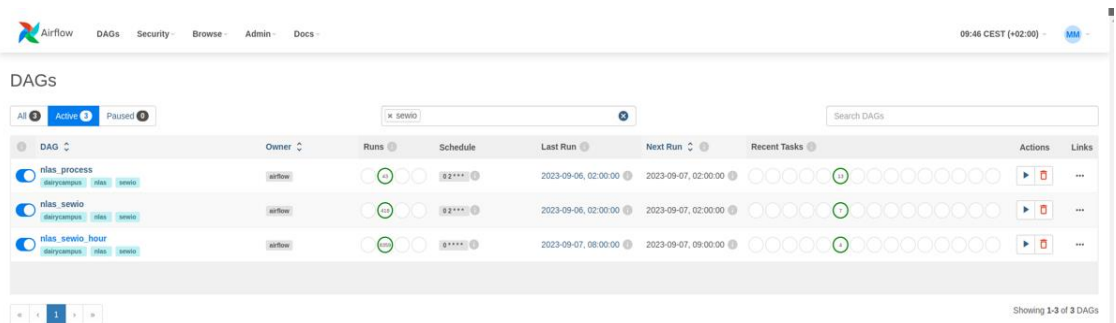
# Data quality control

Control of data quality is extremely important. Tools are developed to control quality at different locations and at different levels

At raw data level

pipelines developed to collect and store raw data

steps within pipelines are monitored to check functioning of these pipelines



The screenshot displays the Airflow web interface for managing DAGs. The top navigation bar includes 'Airflow', 'DAGs', 'Security', 'Browse', 'Admin', and 'Docs'. The current time is 09:46 CEST (+02:00). The main content area is titled 'DAGs' and features a search bar with the query 'n. sewio'. Below the search bar, there are tabs for 'All', 'Active', and 'Paused'. The main table lists three DAGs:

DAG	Owner	Runs	Schedule	Last Run	Next Run	Recent Tasks	Actions	Links
nlas_process <small>dailycampus nlas sewio</small>	airflow	0/10	@2***	2023-09-06, 02:00:00	2023-09-07, 02:00:00	0/10	[Stop] [Refresh] [More]	...
nlas_sewio <small>dailycampus nlas sewio</small>	airflow	0/10	@2***	2023-09-06, 02:00:00	2023-09-07, 02:00:00	0/10	[Stop] [Refresh] [More]	...
nlas_sewio_hour <small>dailycampus nlas sewio</small>	airflow	0/10	@1***	2023-09-07, 08:00:00	2023-09-07, 09:00:00	0/10	[Stop] [Refresh] [More]	...

At the bottom right, it indicates 'Showing 1-3 of 3 DAGs'.

# Data quality control

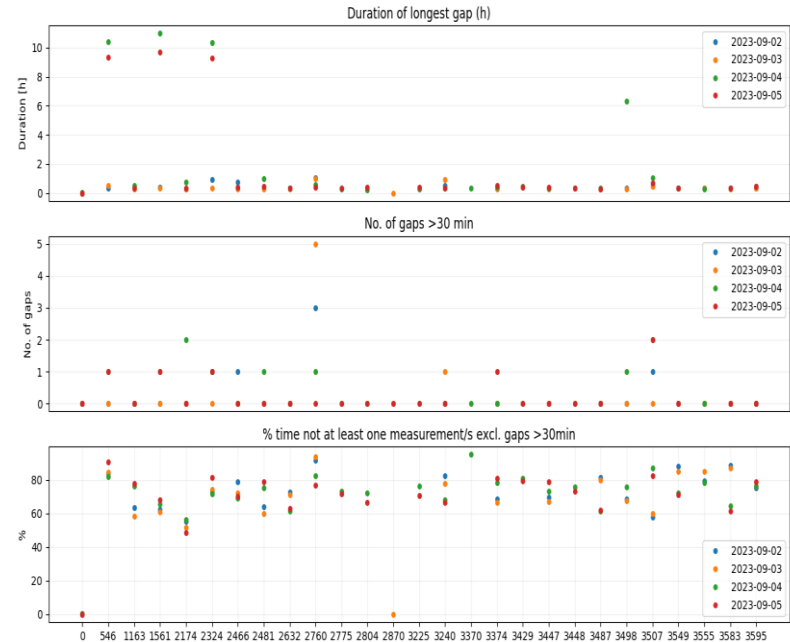
Control of data quality is extremely important. Tools are developed to control quality at different locations and at different levels

At processing of raw data

identify data gaps

impute gaps if possible

check tag position at cow

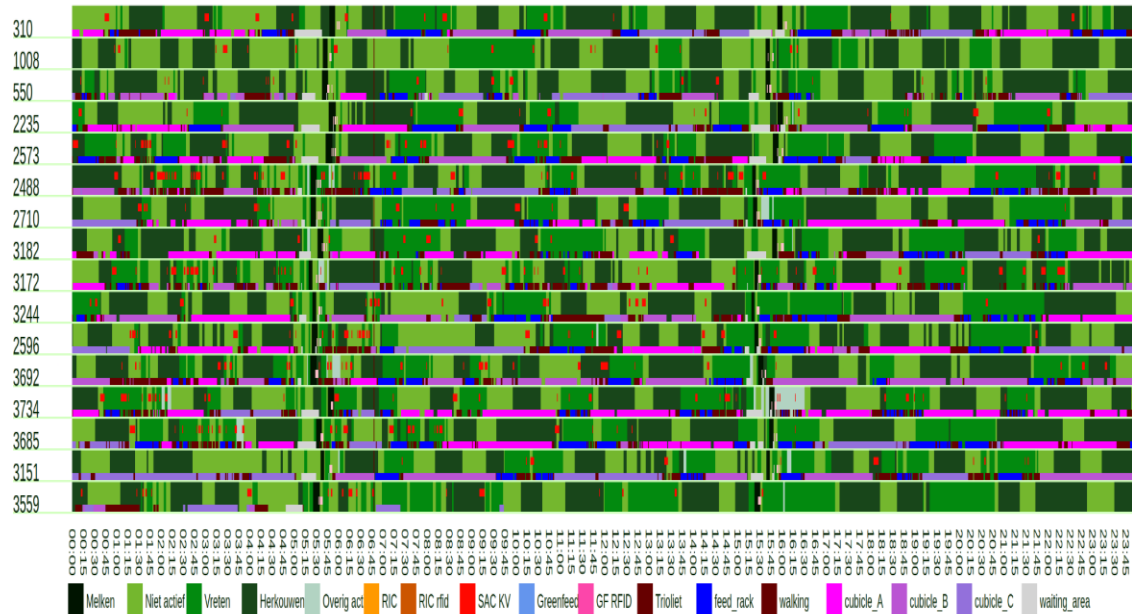


# Data quality control

Control of data quality is extremely important. Tools are developed to control quality at different locations and at different levels

After processing of raw data  
daily basis

*From 7am onwards no  
data on feeding or cubicles  
from tag*



# Outline

Current situation and future perspective

General description of the project

Data architecture at Dairy Campus

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- Data quality control

## **Tools to retrieve relevant information form raw sensor data**

- Locomotion parameters of individual animals*

- Continuous monitoring of behaviour groups of animals

- Automated behaviour in the barn

- Transmission of Digital Dermatitis

Output

# Locomotion parameters of individual animals

## Objective:

Develop tools that allows monitoring of locomotion of individual animals through computer vision

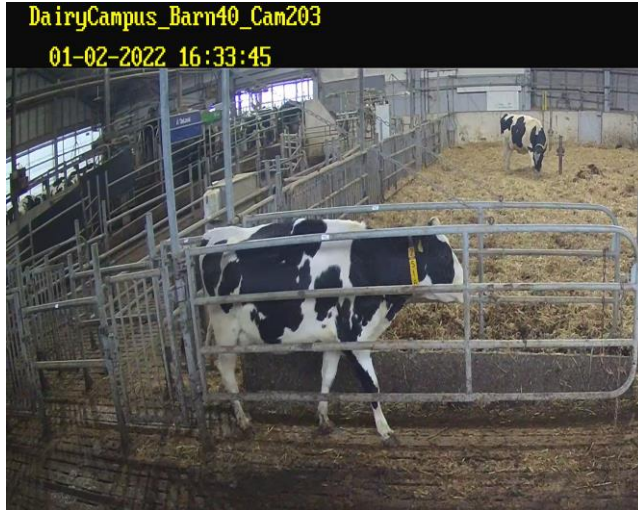
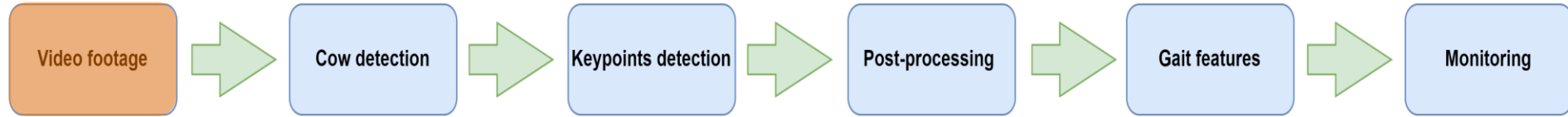
## What is achieved:

From raw video footage via automatically detected anatomical key points to features related to locomotion that we can monitor over time



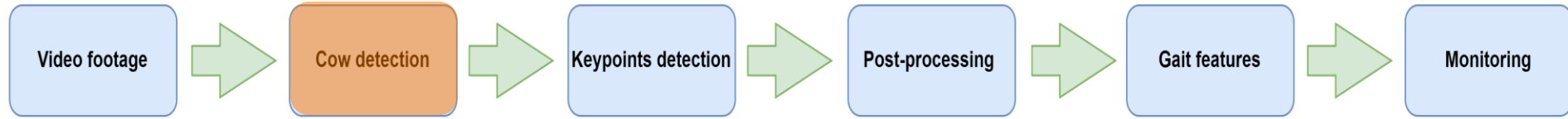
# Locomotion parameters of individual animals

## Pipeline:



Collecting and storing video  
footage, in 1-hour batches  
2\*3 hours/day

# Locomotion parameters of individual animals



## Video example



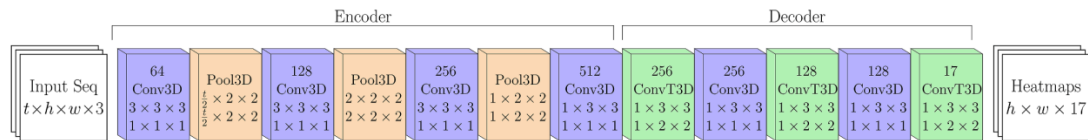
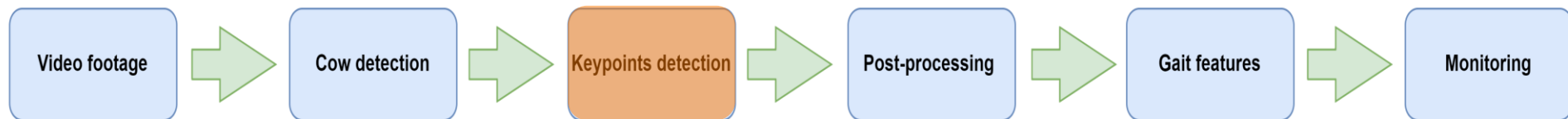
Train and validate on 200 frames with:

❖ *Yolo7 object detection*

**Results:** mean average precision (MAP): 0.95

**Code available:** [https://git.wur.nl/dwz\\_ai/yolo\\_v8/-/commit/c74517b369bc466a3a75d77a48b91a305aeb1dbc](https://git.wur.nl/dwz_ai/yolo_v8/-/commit/c74517b369bc466a3a75d77a48b91a305aeb1dbc)

# Locomotion parameters of individual animals



## Using \*T-leap model:

- Used the temporal information to detect the key-points
- Validated on occluded data

**Code:** <https://github.com/hrussel/t-leap>



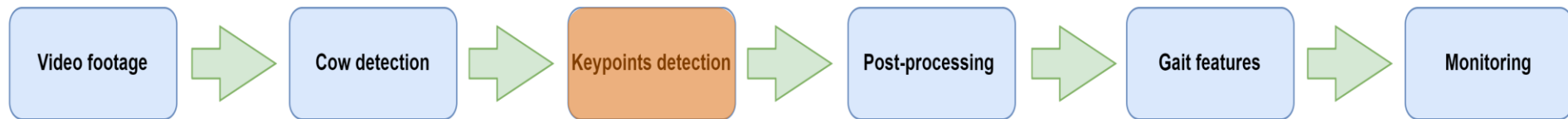
Russello et al. 2022  
T-leap model outside



T-leap model  
retrained for inside



# Locomotion parameters of individual animals



Frames annotated with free and open-source annotation tool CVAT

17 key points per cow per frame

1 left front (LF) hoof, 2 LF fetlock, 3 LF carpal,

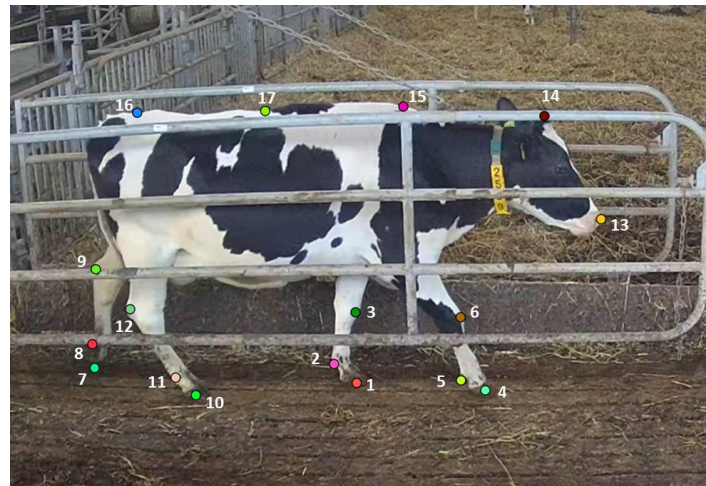
4 Right front (RF) hoof, 5 RF fetlock, 6 RF carpal,

7 Left hind (LH) hoof, 8 LH fetlock, 9 LH carpal,

10 Right hind (RH) hoof, 11 RH fetlock, 12 RH carpal,

13 nose, 14 forehead,

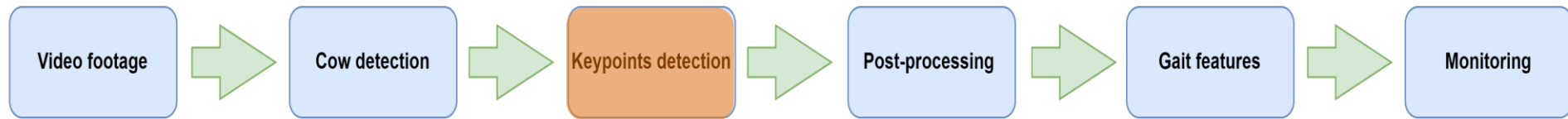
15 withers, 16 sacrum, and 1) caudal thoracic vertebrae.



## Dataset:

W:\ASG\WLR\_Dataopslag\Genomica\Sustainable\_breeding\44 0000 2700 KB DDHT AI 2020\6. data\T-LEAP\Data

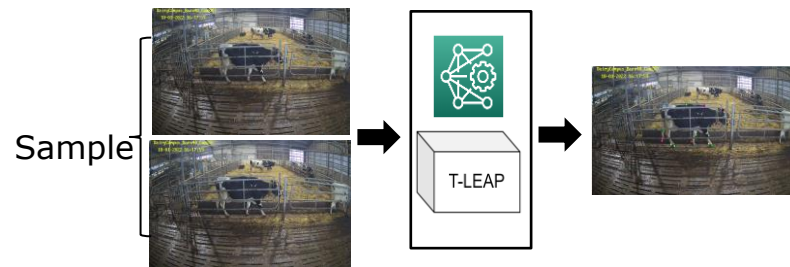
# Locomotion parameters of individual animals



## Train T-leap

### Dataset:

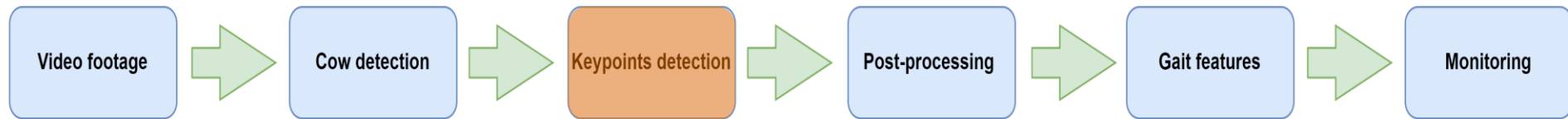
Dataset	Train	Validation	Test	Total
#Cows	22	7	15	44
#Samples	388	108	262	758



### Code:

[https://git.wur.nl/ddht\\_ai/gait\\_analysis/keypoint\\_detection/-/tree/main/frame\\_selection?ref\\_type=heads](https://git.wur.nl/ddht_ai/gait_analysis/keypoint_detection/-/tree/main/frame_selection?ref_type=heads)

# Locomotion parameters of individual animals



## Quantify T-leap model performance – specific key points

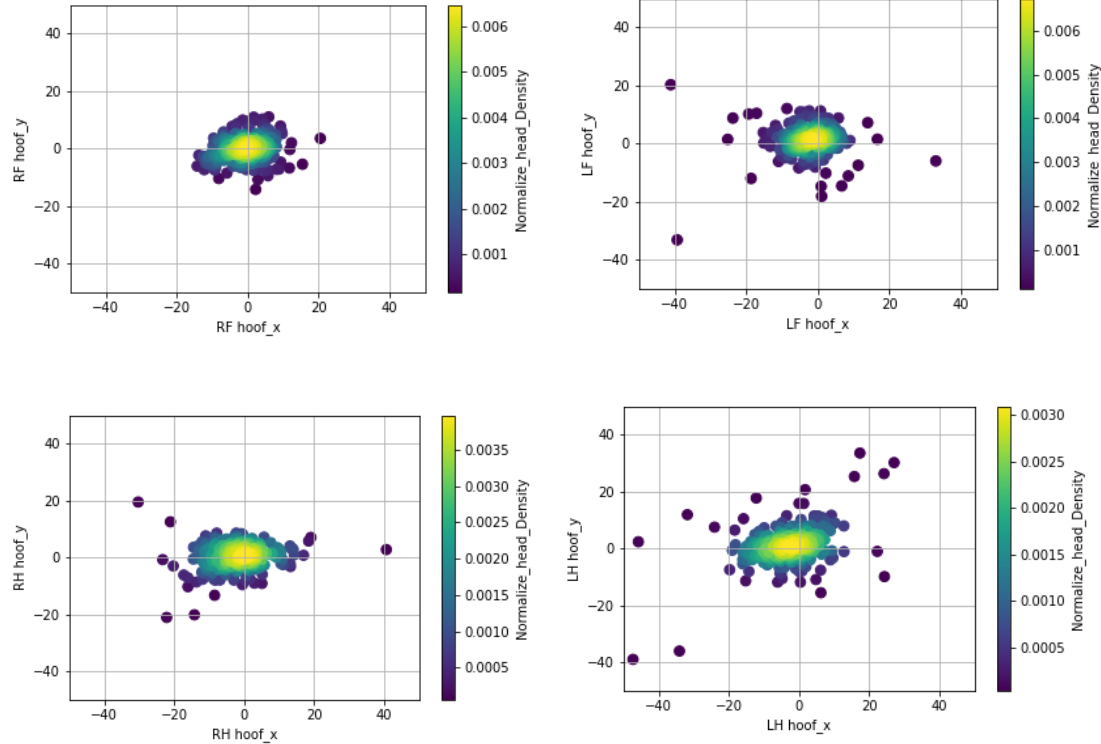
Body parts	Legs	Back	Head
PCKh@0.2	0.96	0.59	0.98
Error-x axis	5.59(±10.63)	28.34(±60.11)	4.52(±6.37)
Error-y axis	4.82(±4.79)	5.87(±6.55)	4.53(±4.66)
Error-x-y axis	8.39(±14.33)	29.85(±60.02)	7.22(+/-7.15)

$$PCKh@\theta = 1/N \sum_{k=1}^{k=N} \delta(\|P_k - T_k\| - head\_size_k * \theta) \quad (\text{eq.1})$$

$$\frac{1}{N} \sum_{K=1}^{k=N} \sqrt{\left(\frac{\dot{x}_k - x_k}{head\_size_k}\right)^2 + \left(\frac{\dot{y}_k - y_k}{head\_size_k}\right)^2} \quad (\text{eq.2})$$

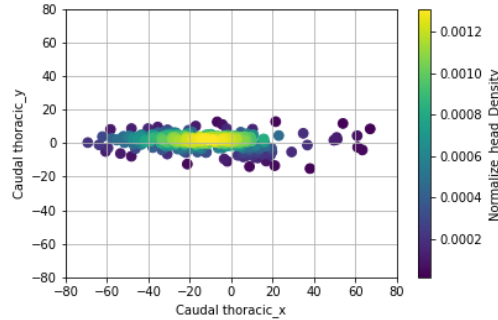
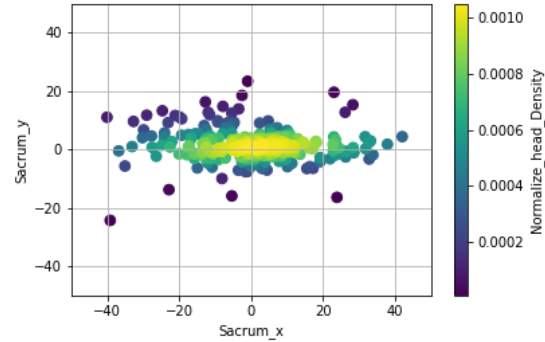
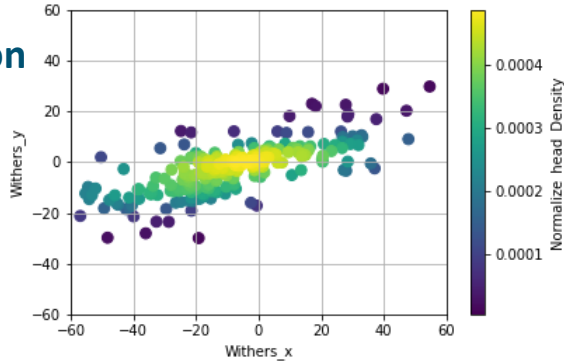
# Locomotion parameters of individual animals

## Error visualisation

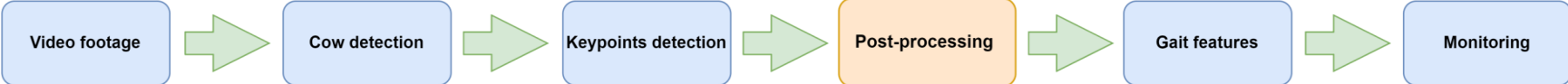


# Locomotion parameters of individual animals

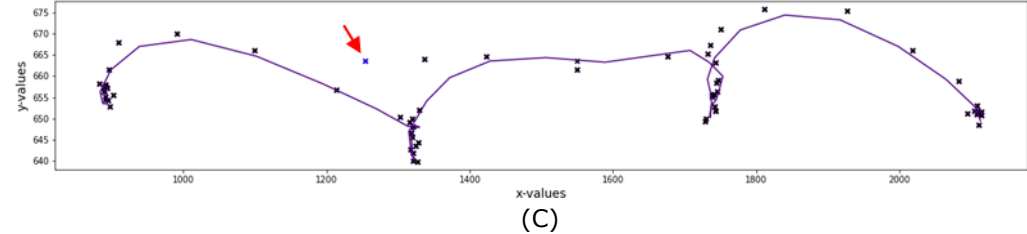
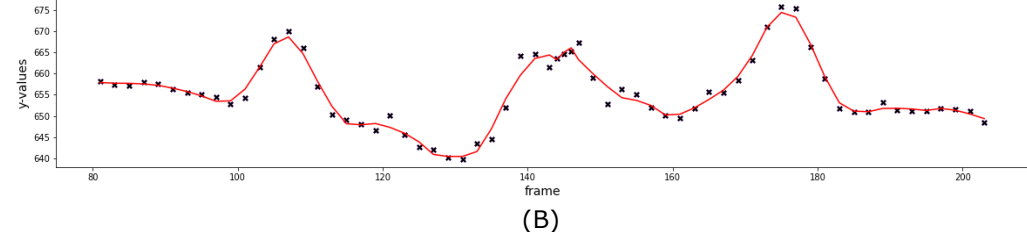
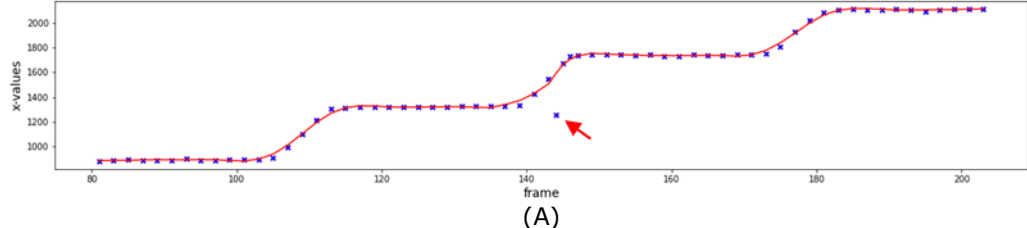
## Error visualisation



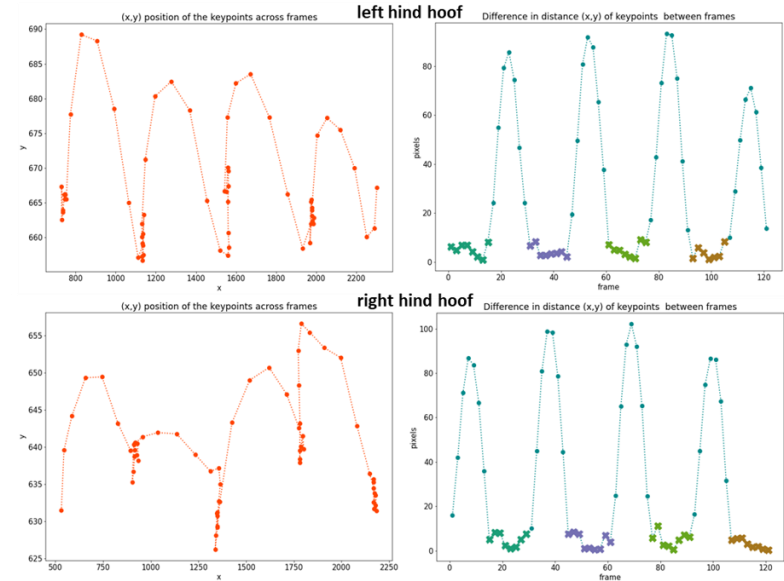
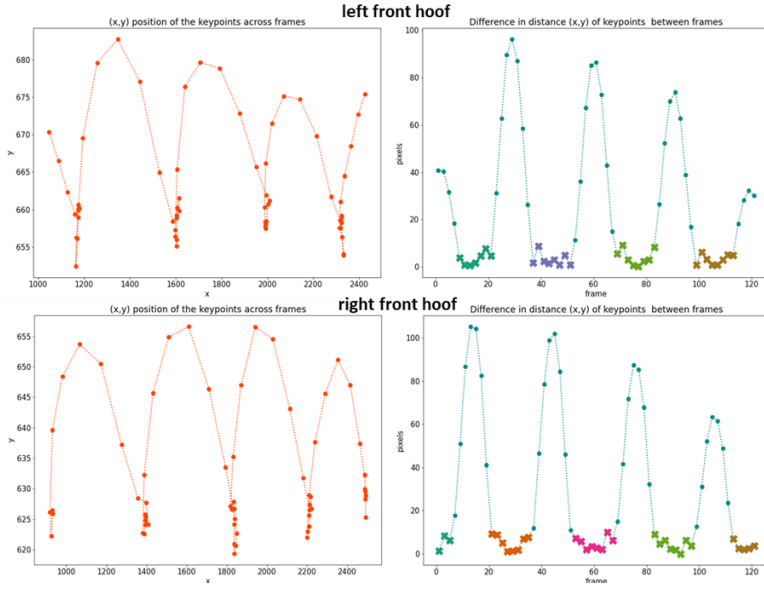
# Locomotion parameters of individual animals



Left Front Hoof



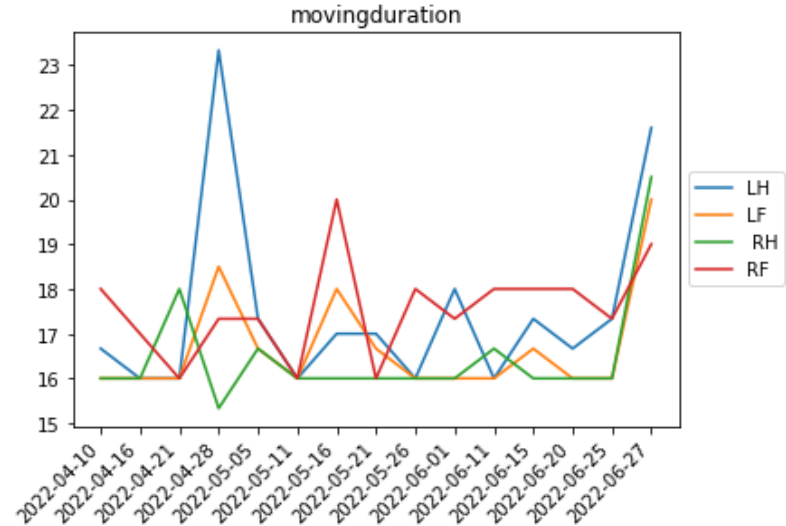
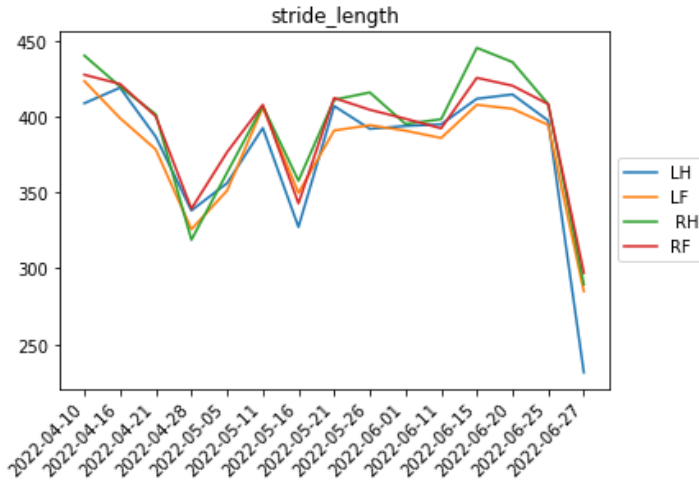
# Locomotion parameters of individual animals



# Locomotion parameters of individual animals



- Gait features from stationarity of hoofs within 15 weeks





# Locomotion parameters of individual animals

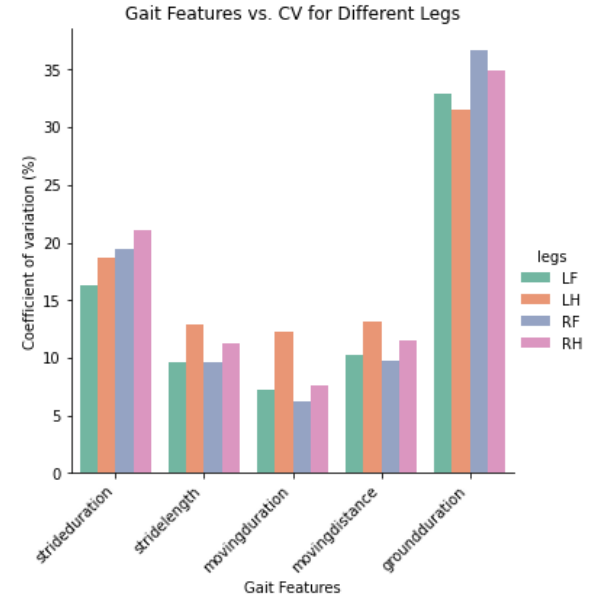
## Repeatability of gait features:

Coefficient of variation (CV)

$$CV (\%) = \left( \frac{\text{Standard deviation}}{\text{Mean}} \right) \times 100$$

## Dataset:

W:\ASG\WLR\_Dataopslag\Genomica\Sustainable\_breeding\44 0000 2700 KB DDHT AI  
2020\6. data\Locomotion\_data\Gait\_features



# Locomotion parameters of individual animals

## **Lessons learned:**

Inaccuracies in cow identification were assigned to the substantial physical distance between the point where cow identification is read by the selection gates and the point where the cow is passing the camera view.  
Cow identification is not solved yet.

To monitor the locomotion of cows, continuous video footage of a cow walking past the camera without interruption is required

# Outline

Current situation and future perspective

General description of the project

Data architecture at Dairy Campus

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- Data quality control

## **Tools to retrieve relevant information form raw sensor data**

- Locomotion parameters of individual animals

- Continuous monitoring of behaviour groups of animals*

- Automated behaviour in the barn

- Transmission of Digital Dermatitis

Output

# Monitoring behaviour of groups of animals

## Objective:

Develop tools that allows continuous monitoring of behaviour of **groups of animals** through **computer vision** and **tracking sensors**

## What is achieved:

Calibration of the camera setup and realignment of the cameras

Tools to obtain 3D positions of key points and identify individual cows in a group from raw video footage

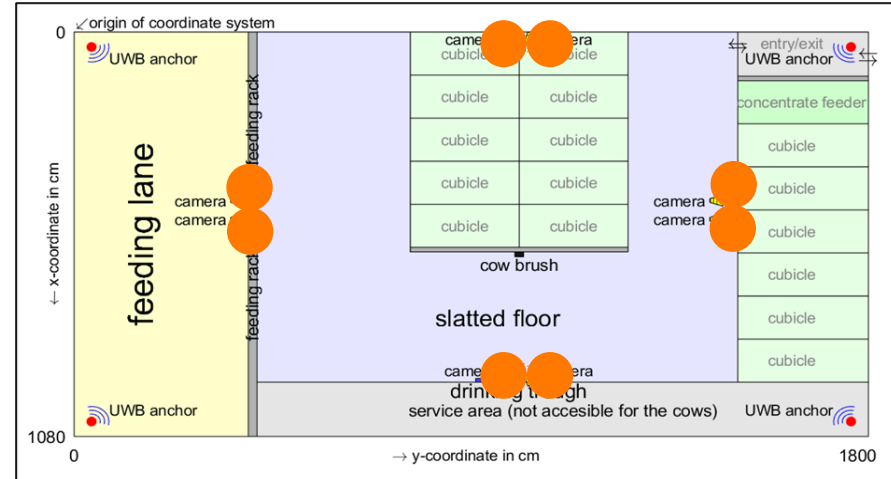
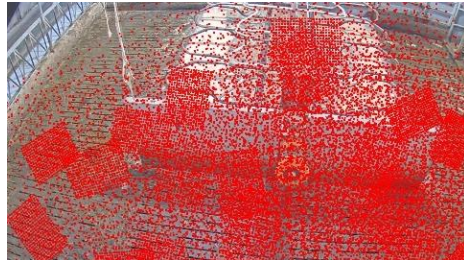
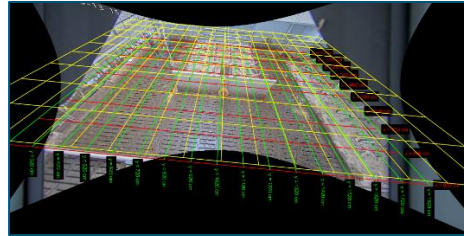
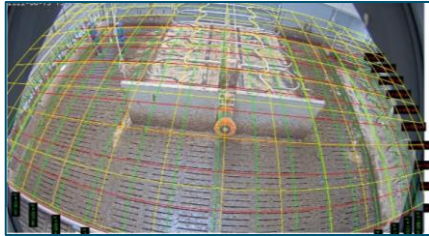
Tools converting raw position data into behaviours



# Monitoring behaviour of groups of animals

## Through video footage

Calibration and synchronisation of a multi-camera system (individual and stereo)



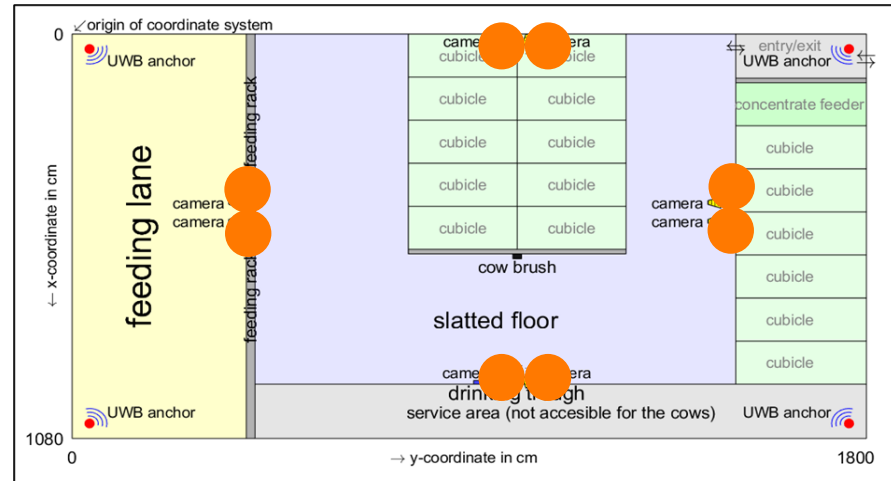
8 cameras (Viso, Noldus) in 1 of the research units (16 cows).

# Monitoring behaviour of groups of animals

## Through video footage

Calibration and synchronisation of a multi-camera system (individual and stereo)

Relate pixels to 3D positions (in 'real-world' coordinates) of each camera -> triangulation -> 3D positions of keypoints



8 cameras (Viso, Noldus) in 1 of the research units (16 cows).

# Monitoring behaviour of groups of animals

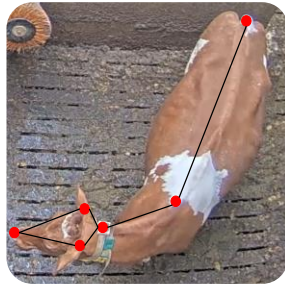
After calibration of the multi-camera system and relating pixels to real-world coordinates the following work flow to get to behaviour monitoring

Per camera step 1 and 2, and at step 3 multiple camera views are combined and integrated into 3D key points that are tracked over time. Step 4 is future work.



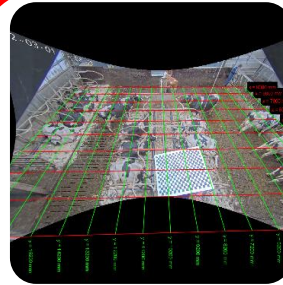
## Step 1

Object detection  
and tracker



## Step 2

Keypoint detection  
and tracker



## Step 3

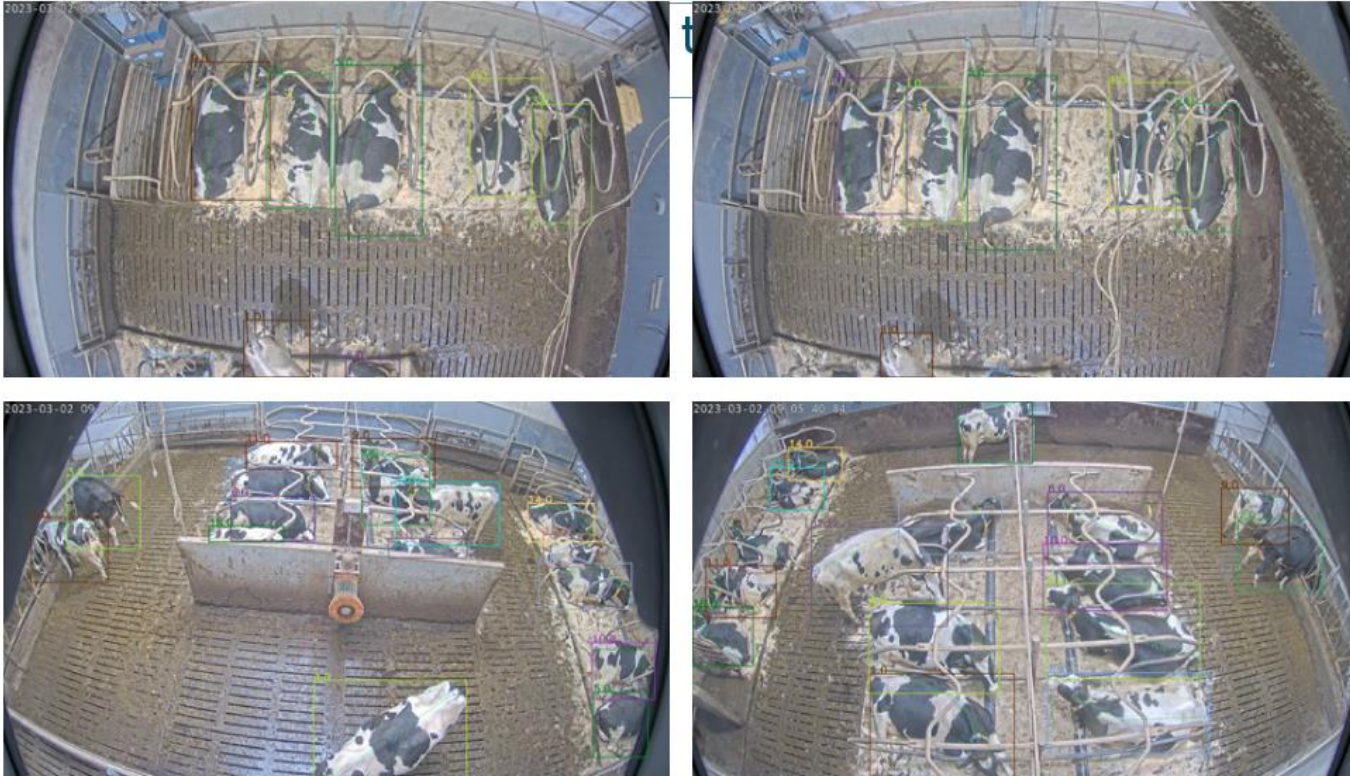
Integration of  
multiple views to  
3D tracker



## Step 4

Behaviour  
recognition  
(patterns)

# Monitoring behaviour of groups of animals



Input:  
synchronised  
video footage

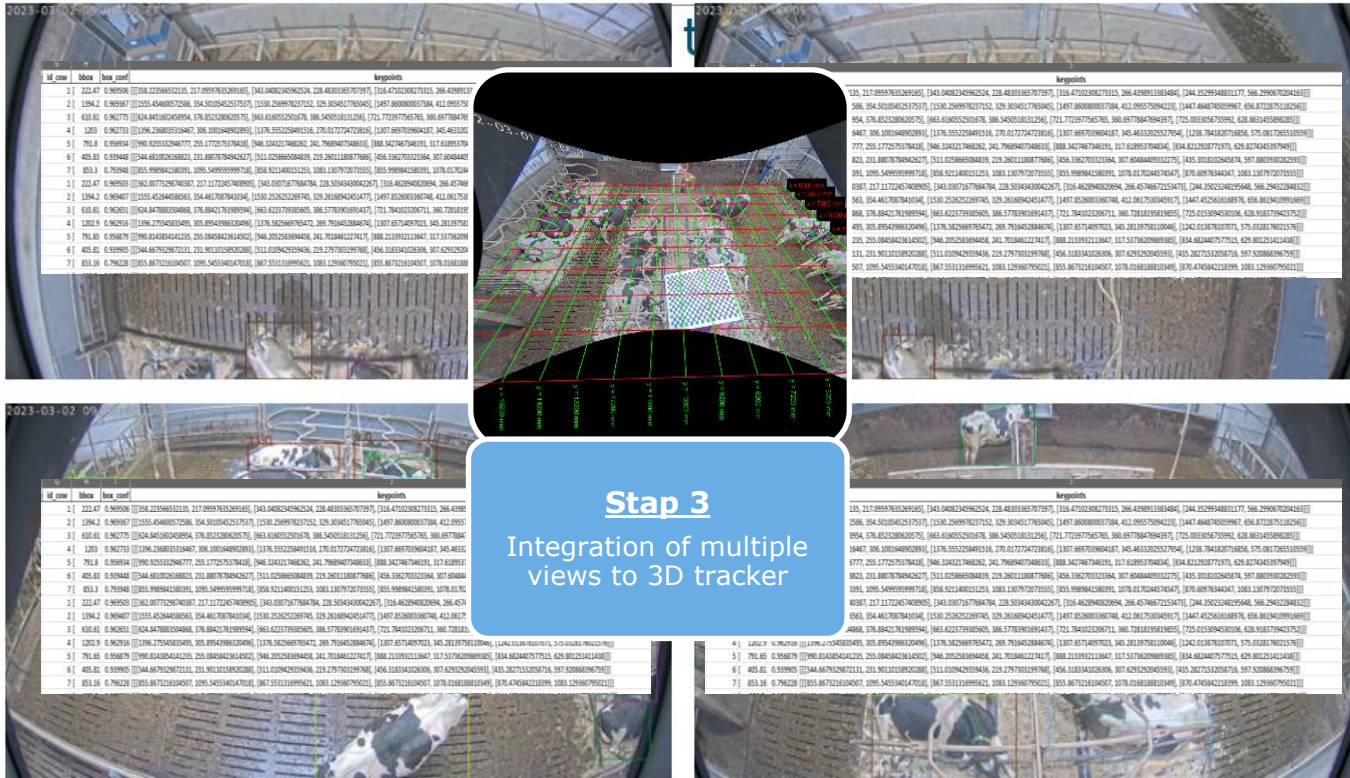
Approach: for  
each camera

- cow detection  
(bounding boxes)
- keypoint detection

Integration:  
pixels to 3D  
coordinates



# Monitoring behaviour of groups of animals



# Monitoring behaviour of groups of animals

## Through tracking

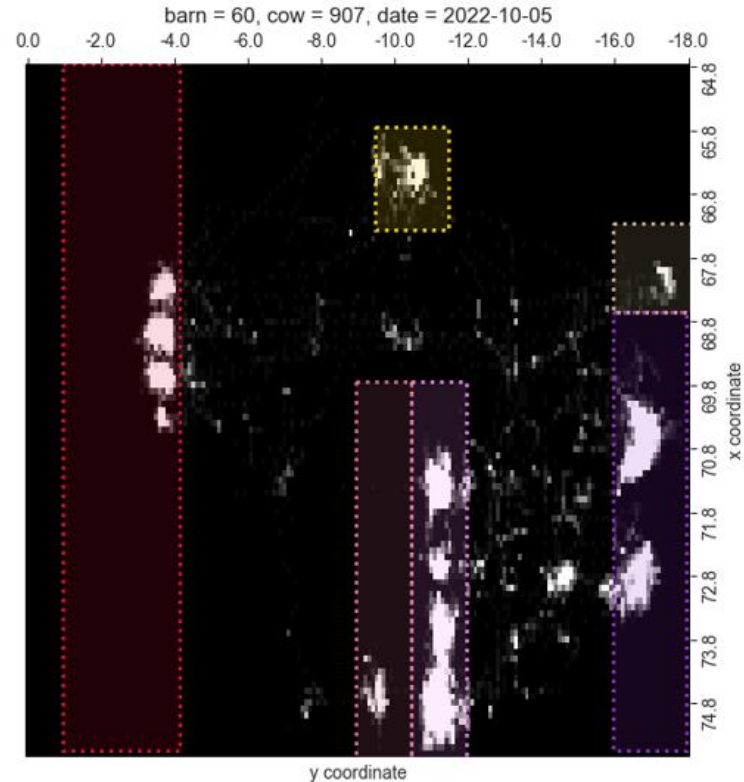
Raw position data from hardware Sewio

7 research units and waiting area  
110 cows (of which 32 with 10Hz/sec)

Pre-process raw XY data to 1 XY-position / cow ID / second

Median smoothed, rolling window filter  
Minimum distance travelled filter, data imputations, filter area edges, add cow identification

Link XY-position with 'real-world' coordinates of research unit and waiting area

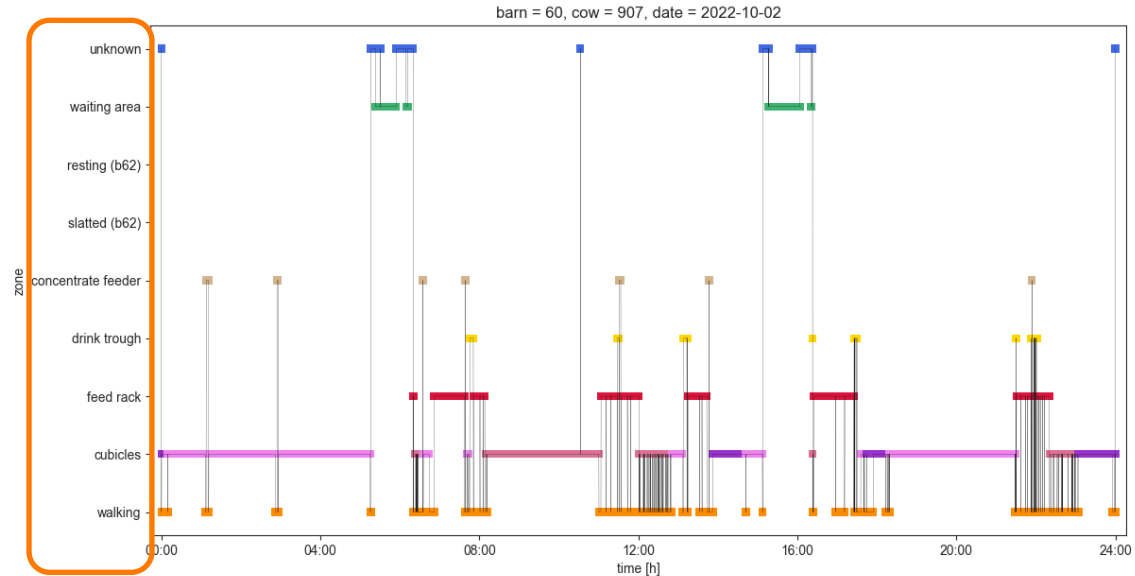
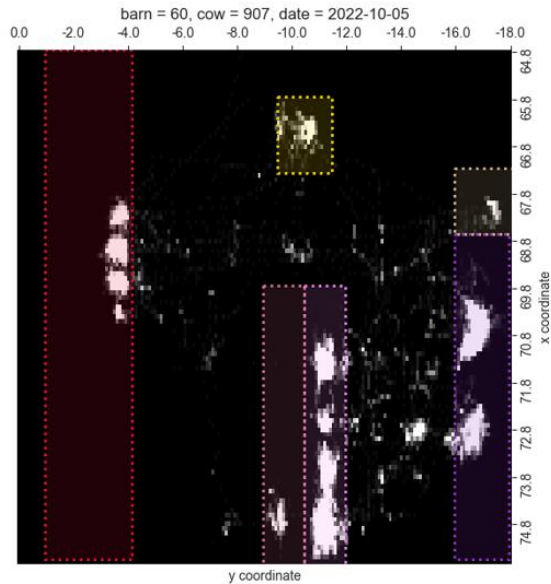


Heat map of XY positions of one cow during one day

# Monitoring behaviour of groups of animals

## Through tracking

XY-positions over the day are assigned to a location in the barn. Location can be used to assign behaviour per cow per day



# Monitoring behaviour of groups of animals

## **Lessons learned:**

Pre-installation preparation can be improved considerably

Camera calibration & multiple camera setup have advantages for processing

Annotation of video footage can best be done iteratively

Long term collection of sensordata with high temporal resolution with standard tracking sensors is considerably more difficult than expected

Accelerometer data collected with such devices has limited useability.

# Outline

Current situation and future perspective

General description of the project

Data architecture at Dairy Campus

- Installation of hardware and software

- Data quality control

## **Tools to retrieve relevant information form raw sensor data**

- Locomotion parameters of individual animals

- Continuous monitoring of behaviour of groups of animals

- Automated behaviour in the barn*

- Transmission of Digital Dermatitis

Output

# Automated behaviour in the barn

## Objective:

Noldus main objective is to provide a large scale monitoring system to continuously record location and activity data which facilitates researchers to get insights in movement and behavior patterns of dairy cattle in the different barns at the Dairy Campus.



Noldus provided two behavioral monitoring systems for cattle:

- TrackLab, a tag-based location and activity tracking system using Ultra Wide Band radio technology.
- Viso, a video camera system controlling and synchronizing multiple camera streams.



# Automated behaviour in the barn

## Achievements

Successful deployment of TrackLab, a large tracking system for analysis of dairy cow movement and behavior at Dairy Campus

8 departments/pens divided over two barns (environmental barn and waiting area)

Up to 130 dairy cows can be tracked continuously and visualized on a map in real-time

Accuracy of tag UWB location data has been validated. Accuracy and precision is  $<20$  cm

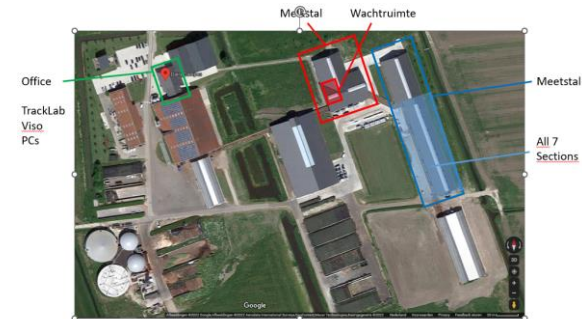
Optionally with individual accelerometer data (at sample rate  $\sim 10$  Hz)

Successful deployment of Viso, a video and audio recording system

8 Axis IP cameras, 4 different views, in one barn (72)

Successful integration of both tools in Dairy Campus computer network

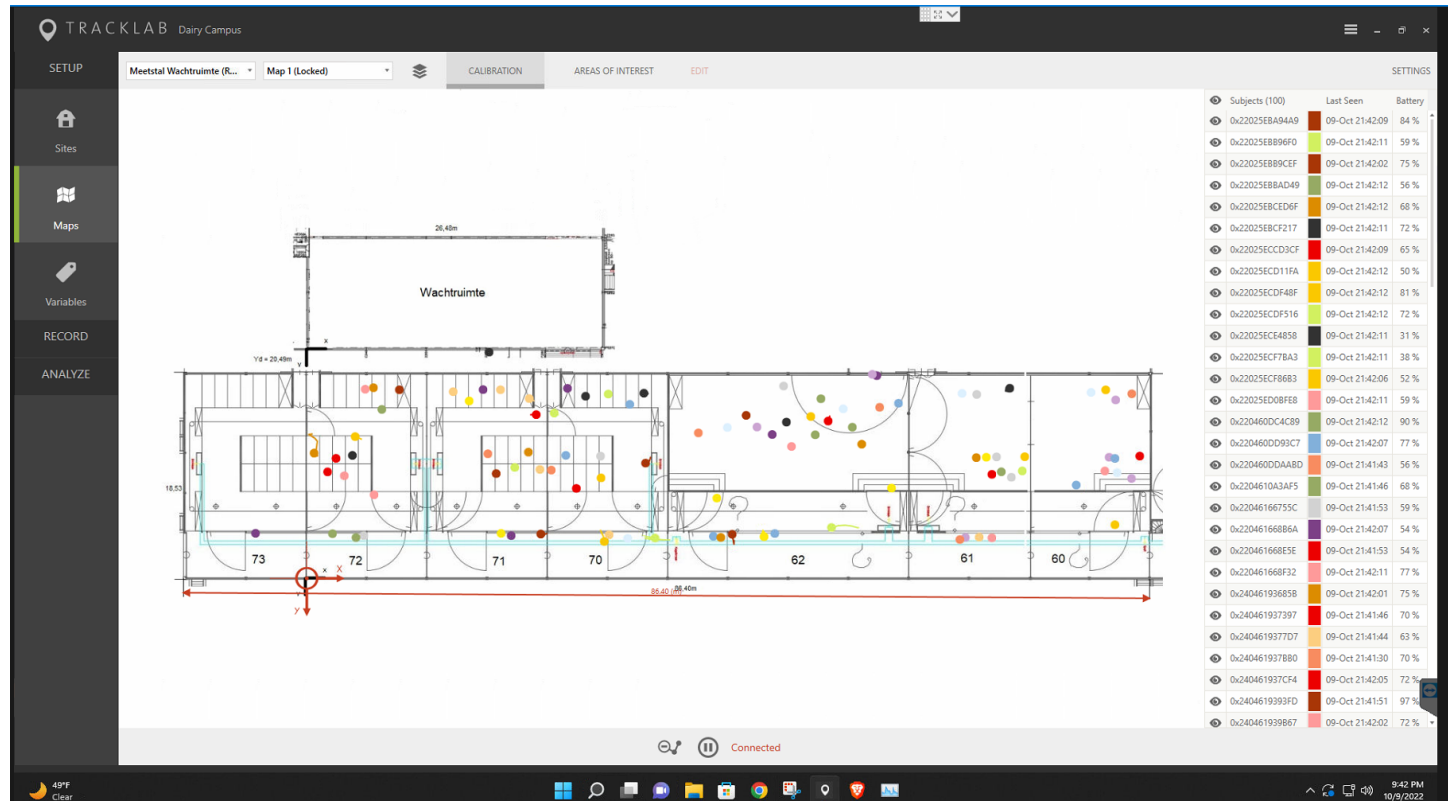
Data is directly available and streamed on WUR network



# Automated behaviour in the barn

## Achievements

TrackLab LIVE  
visualization of  
individual  
dairy cows







# Automated behaviour in the barn

## Lessons learned

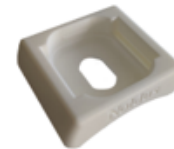
Collaboration from people in the field, Dairy Campus employees, researchers from WUR and technical people from Noldus lead to optimal use and integration of the tools

Use of individual cow tags requires administration and human labor to attach and remove the tags from the cow neck collars to recharge the battery. Minimize human labor but get maximum data collected.

System hardware redesigns are made to cope with the barn environment

- New robust tag collar adapters

- New extended UWB anchor wall mounts for optimal tracking



Collected dairy cattle data is a very valuable source for research and development of (machine learning) algorithms that give insight of animal behavior and indicators for health. Ongoing and future work.

# Automated behaviour in the barn

## Lessons learned

TrackLab and Viso showed to be useful tools for Dairy Campus / researchers / farmers  
(from: BSc thesis by Rik Dekker)

Precise location recording of cows, valuable for research and management

Registration (history) of cows (research groups)

Where, which cow, what time (important for barn experiments)

Continues monitoring enables detection of changes and alerts

Reusable cow tags (individually rechargeable and reconfigurable)

Analysis for research purposes

Different built in standard analysis possibilities (activity, area or socially related)

For user defined time periods

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- Automated behaviour in the barn

- Transmission of Digital Dermatitis*

Output

# Detection and transmission of Digital Dermatitis

## Objective:

1. Study transmission of the infectious claw disease Digital Dermatitis (DD) in dairy cattle
2. Investigate the genetic and environmental factors contributing to transmission

## What is achieved:

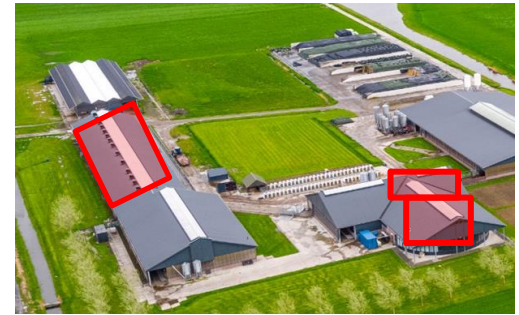
Installation of hardware (cameras and protection box) at milking parlour within DC for normal functioning under troublesome conditions and limitations

A basic maintenance and cleaning protocol for hardware was implemented

A basic algorithm prototype for computer vision detection of DD-sick/healthy claws during milking

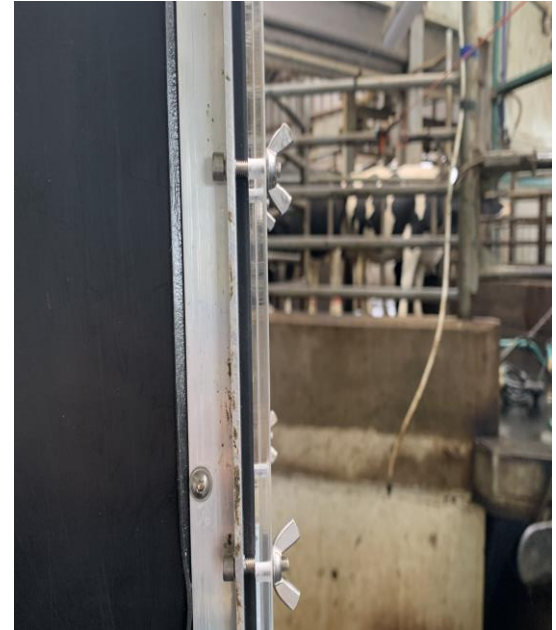
A discrete time and space agent-based model of SARS-COV-2 transmission (PeDVIS COVID) was adapted

for modelling environmental transmission of DD within farm



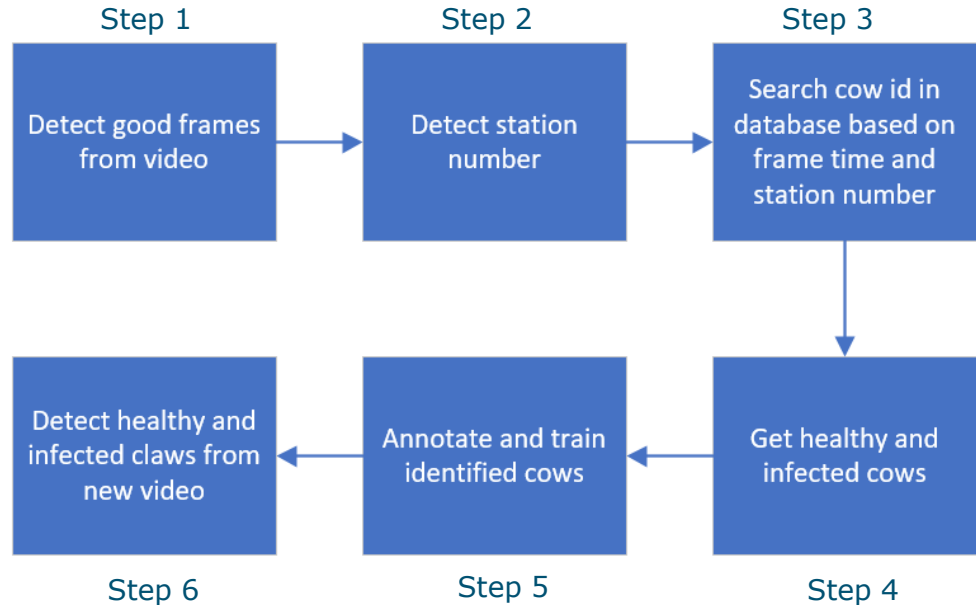
# Detection and Transmission of Digital Dermatitis

Hardware installed in the milking parlour for automated detection



# Detection and Transmission of Digital Dermatitis

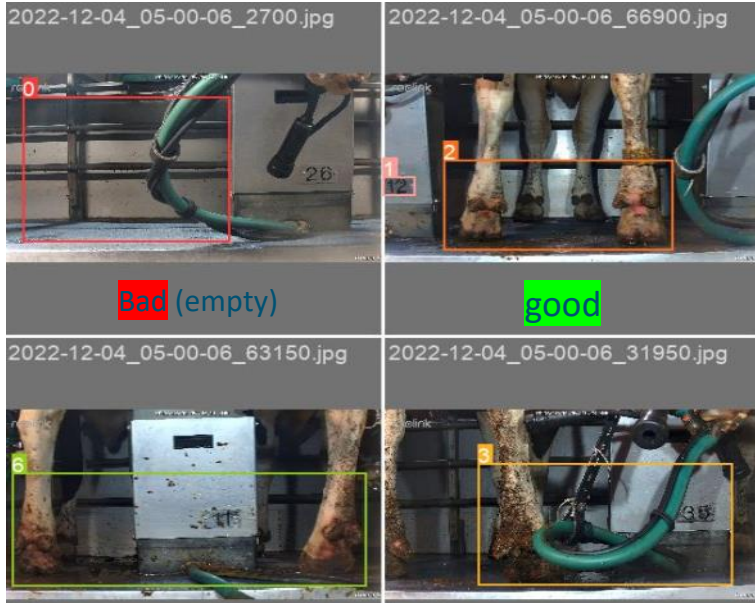
Algorithm for automated detection of DD through computer vision



# Detection and Transmission of Digital Dermatitis

## Results of detection algorithm

### 1. Detect good frame



### 2. Detect station number



### 3. Search cow Id

index	CowId	DateTime	Station
36	3295	2022-12-05 16:19:00	2
37	1586	2022-12-05 07:07:00	2
38	1133	2022-12-05 18:03:00	2
39	3314	2022-12-05 16:59:00	2
40	2725	2022-12-05 05:11:00	2
41	1427	2022-12-05 06:15:00	2
42	628	2022-12-05 17:28:00	2
43	1218	2022-12-05 15:43:00	3
44	3037	2022-12-05 06:13:00	3
45	2472	2022-12-05 07:51:00	3
46	3163	2022-12-05 16:32:00	3
47	1607	2022-12-05 18:03:00	3
48	2439	2022-12-05 17:32:00	3
49	8239	2022-12-05 07:05:00	3
50	2266	2022-12-05 07:23:00	3



# Detection and Transmission of Digital Dermatitis

## Results of detection algorithm

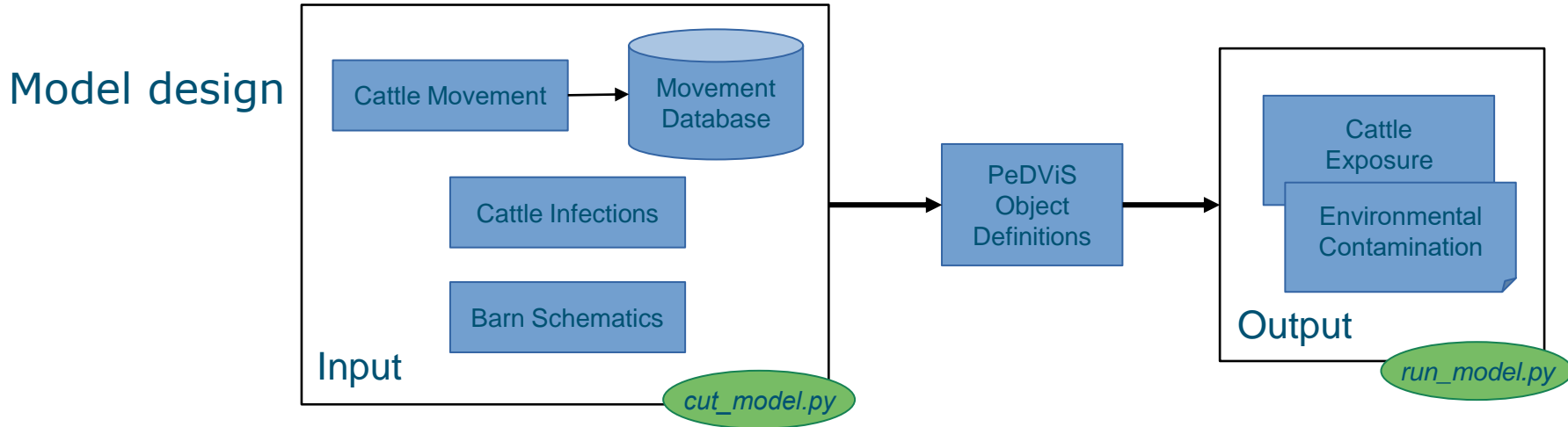
### 4. Detected infected claws



Left (healthy), Right(infected)

# Detection and Transmission of Digital Dermatitis

Transmission model developed with cattle tracking data generated and collected during the project (n = 193 cows) and claw DD status obtained during three months of milking sessions



# Detection and Transmission of Digital Dermatitis

## Model design

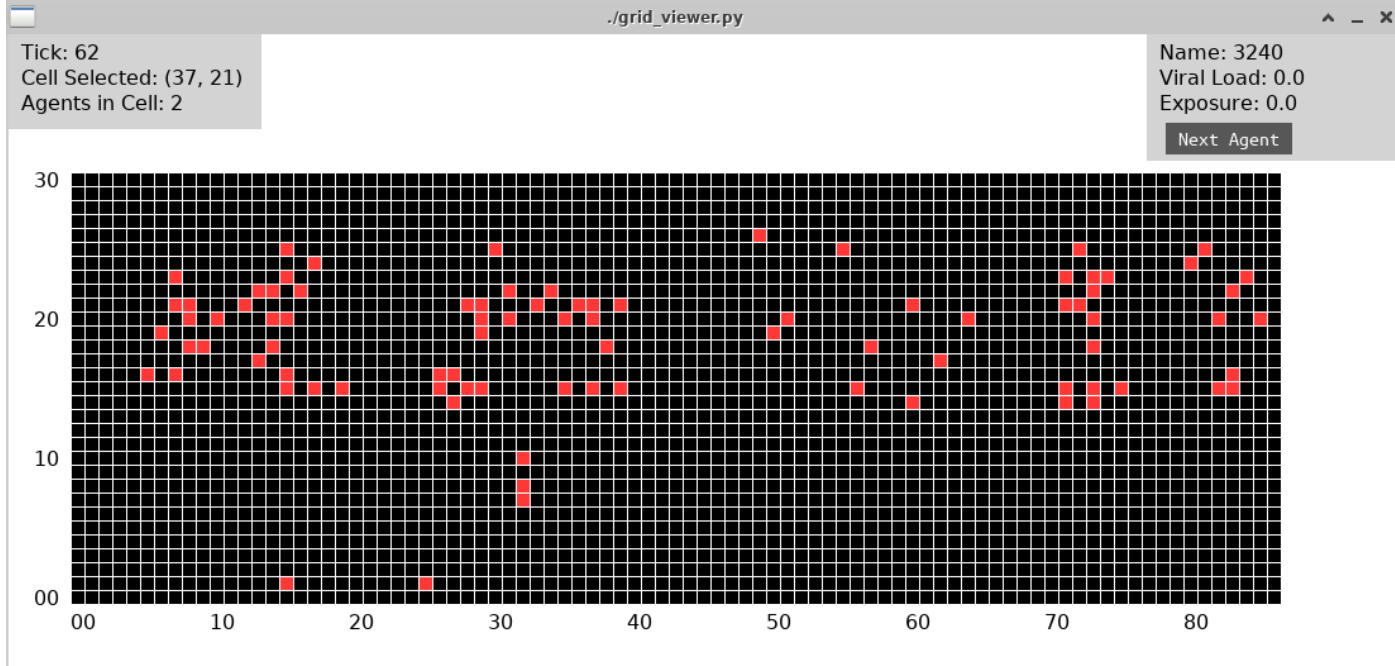
### Environment

- Height x width grid of cells, units set by user
- Grid represents cattle movement over time
- Grid holds 'contamination' emitted by infected cattle

### Agents

- Cattle themselves and their movement 'script'
- Tracks contamination, total and location specific

# Movement Grid



# Detection and Transmission of Digital Dermatitis

## **Lessons learned:**

Computer vision of specific lesions and disease stages under commercial operations presented several challenges and need more time and efforts to be optimized

Hardware adequacy needed for working conditions on commercial farms should be optimized and long-term use tested

Maintenance and lens cleanliness protocols should be optimized and adapted to many different farm conditions and settings

Our system was satisfactory for carousel milking systems but should be adapted for herring-bone or robot systems

# Detection and Transmission of Digital Dermatitis

## **Lessons learned:**

We used limited cattle tracking data and claw DD status; however; we were able to show that environmental transmission can be detected

More data (coming from more animals and extended time-period) is needed for:

- calibrating the model in terms of bacterial emission, pickup, and decay onto the contamination layers

- grid refinement and integration of different sources of data (behaviour, animal direction, etc.)

- evaluate the genetic and environmental factors contributing to transmission

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Tools to retrieve relevant information form raw sensor data

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- Continuous monitoring of behaviour of groups of animals

- Automated behaviour in the barn

- Transmission of Digital Dermatitis

## Output

# Output

## Locomotion parameters of individual animals

A large amount of raw video footage at secured data storage WLR that is currently largely unexplored

Several annotated datasets at secured data storage WLR

- Key points for retraining T-leap

- Gait features

Several scripts stored at gitlab

- [https://git.wur.nl/ddht\\_ai/gait\\_analysis/keypoint\\_detection/tree/main/frame\\_selection?ref\\_type=heads](https://git.wur.nl/ddht_ai/gait_analysis/keypoint_detection/tree/main/frame_selection?ref_type=heads)

- [https://git.wur.nl/ddht\\_ai/gait\\_analysis/gait\\_features](https://git.wur.nl/ddht_ai/gait_analysis/gait_features)

- [https://git.wur.nl/dwz\\_ai/yolo\\_v8/-/commit/c74517b369bc466a3a75d77a48b91a305aeb1dbc](https://git.wur.nl/dwz_ai/yolo_v8/-/commit/c74517b369bc466a3a75d77a48b91a305aeb1dbc)

- <https://github.com/hrussel/t-leap>

- [https://git.wur.nl/dwz\\_ai/kb\\_ai](https://git.wur.nl/dwz_ai/kb_ai) (cow detector and keypoint detector for barn video footage)



# Output

## **Continuous monitoring of behaviour of groups of animals**

A large amount of raw sensor data (including video footage) at secured data storage WLR that is currently largely unexplored

Several annotated datasets at secured data storage of WLR

Bounding boxes for training the cow detector model  
keypoints for training the keypoint detector model

Some examples of processed video footage at secured data storage of WLR

Several scripts stored at gitlab

[https://git.wur.nl/dwz\\_ai/kb\\_ai](https://git.wur.nl/dwz_ai/kb_ai)

# Output

## **Automated behaviour in the barn**

Multi model dairy cattle Data Set has been created for research purposes

- Data collected for a week from 16 dairy cows at Dairy Campus

  - Accelerometer and location data at high sample rate (20 Hz)

  - Detailed video recordings (5 different camera views including hay rack and waterbin)

- Human labeled/annotated behavior events using the video recording (partially)

- All data is imported and synchronized in The Observer XT software from Noldus

Contact Noldus when interested in this data set:

[www.noldus.com/contact](http://www.noldus.com/contact)

# Output

## Detection and transmission of Digital Dermatitis

A large dataset of cattle movement files were transformed into formatted agent *scripts*

sqlite database files containing daily movements of each cattle in the experimental barn  
a movement visualization tool to check movement file transformation

All code is in a GIT version control repository hosted by the WUR Data Competence Center

A python script '*cut\_model*' was written to produce both the environment definitions and the agents with their movement scripts

The model outputs data is a grid of contamination by coordinates across time and a list of contamination that an agent has been exposed to, across time

The output data is stored as such

# Output

## Other output

### Thesis

Doornenbal, J., 2022. Adviesrapport drinkgedrag. Rapportage studentenonderzoek VHL.

Dekker R., 2022, Noldus TrackLab en Viso als managementtool voor Dairy Campus? Een verkenning naar de (on)mogelijkheden. BSc thesis. [informatie@dairycampus.nl](mailto:informatie@dairycampus.nl)

### Popular press

De technologie houdt een oogje in het zeil. Een zesde zintuig voor de boer. Nienke Beintema. 2022. WageningenWorld|3. <https://edepot.wur.nl/582933>

Camera's verraden de gezondheid van de koe. Nienke Beintema. 2022. Resource. <https://edepot.wur.nl/582175>

# Output

## Popular press (continued)

Onderzoekers Dairy Campus willen kreupele koeien via camera's vroeg herkennen. Guus Daamen.2022 Melkvee. <https://www.melkvee.nl/artikel/459072-onderzoekers-dairy-campus-willen-kreupele-koeien-via-cameras-vroeg-herkennen/>

Smart technology helps track and improve cow health. 2022. [https://www.youtube.com/watch?v=V\\_FPqSx0Upk&t=8s](https://www.youtube.com/watch?v=V_FPqSx0Upk&t=8s)

Camera's voor gezonde hoeven. 2023. <https://magazines.wur.nl/nlas-magazine-nl/cameras-voor-gezonde-hoeven>

Een camerasysteem detecteert kreupele koeien automatisch. 2023. [Een camerasysteem detecteert kreupele koeien automatisch – Dairycampus](#)

Continue monitoren op gezondheid loont. Janet Beekman. 2023. Boerderij 108 – no 50 (13 September 2023)

# Output

## Presentations

Ouweltjes, W., Next level animal science: monitoring behaviour. Webinar Japan-Netherlands on digital dairy farming & AW assessment, January 28, 2022.

Taghavi M., Russello H., Ouweltjes W., Kamphuis C., Adriaens I. 2022. Automated gait analysis with a deep learning key point detection model. 10<sup>th</sup> European Conference on Precision Livestock Farming (ECPLF), Vienna, Austria

Koning de., C., C. Kamphuis, W. Ouweltjes, Digital Dairy Developments. 2022. World Agri-Food Innovation, Beijing, November 28, 2022

Kamphuis C., Data een blik in de toekomst. 2023. Data Dairy Dag bij Dairy Campus, Leeuwarden, September 19, 2023

## Scientific output

Taghavi M., Russello H., Ouweltjes W., Kamphuis C., Adriaens I. 2023. Cow key point detection in indoor housing conditions with a deep learning model. Accepted for publication in Journal of Dairy Science.